

# Kinematics & Dynamics of Linkages

## Lecture 15: Mechanical Advantage

# Power in a Systems

## Mechanical System

Dot product of the force vector  $F$  and the velocity  $V$

$$P = F \cdot V = F_x V_x + F_y V_y$$

## Rotating Systems

Dot product of the torque  $T$  and the angular velocity  $V$

$$P = T\omega$$

# Energy loss



$$losses = P_{in} - P_{out}$$

**Mechanical efficiency**  $\varepsilon = \frac{P_{out}}{P_{in}}$

# Ideal Case

$$P_{in} = P_{out}$$

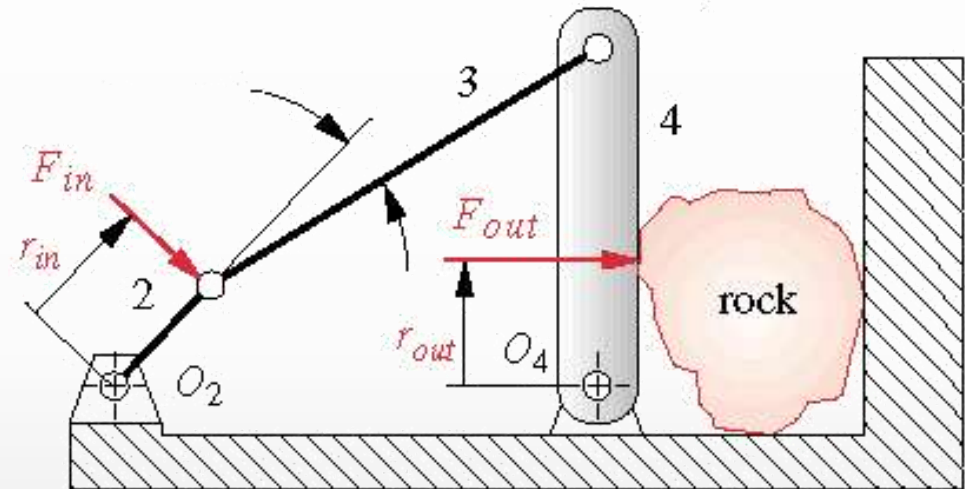
$$P_{in} = T_{in} \omega_{in}$$

$$P_{out} = T_{out} \omega_{out}$$

$$T_{in} \omega_{in} = T_{out} \omega_{out}$$

$$\frac{T_{out}}{T_{in}} = \frac{\omega_{in}}{\omega_{out}}$$

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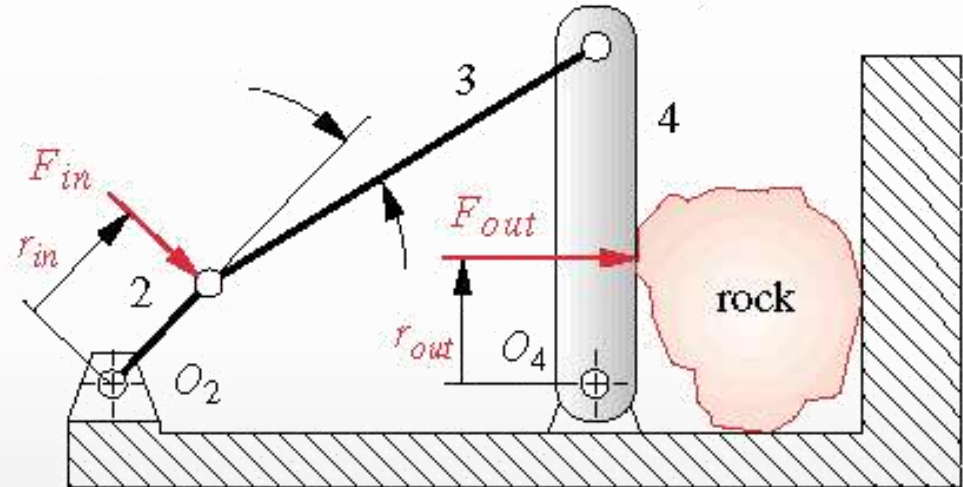


# Ideal Case

Input Force  $F_{in}$

Output Force  $F_{out}$

$$F_{out} = \frac{T_{out}}{r_{out}} \quad F_{in} = \frac{T_{in}}{r_{in}}$$



Mechanical Advantage

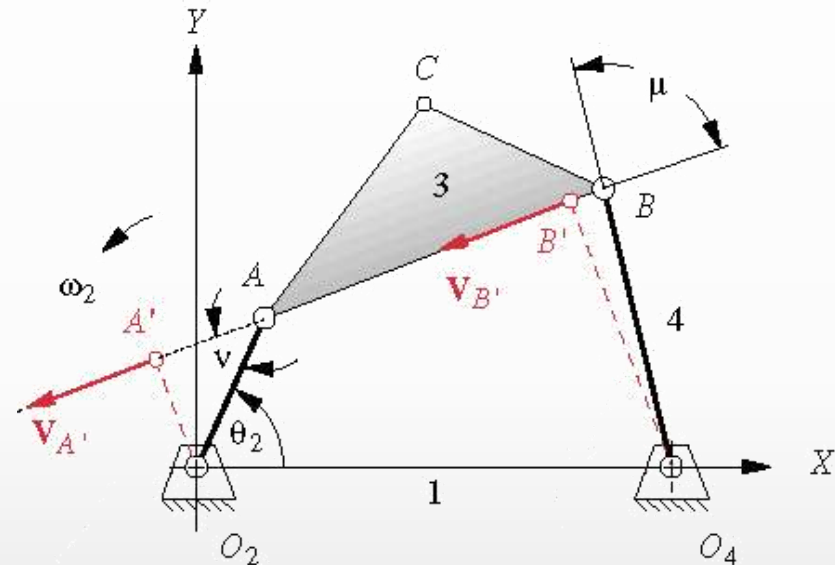
$$m_A = \frac{F_{out}}{F_{in}} = \frac{T_{out}}{T_{in}} \frac{r_{in}}{r_{out}} = \frac{\omega_{in}}{\omega_{out}} \frac{r_{in}}{r_{out}} = \frac{V_{in}}{V_{out}}$$

# Mechanical Advantage - 4 Bar Linkage

From Velocity Analysis

$$\omega_4 = \frac{a\omega_2 \sin(\theta_2 - \theta_3)}{c \sin(\theta_4 - \theta_3)}$$

But 
$$\frac{\omega_4}{\omega_2} = \frac{O_2A \sin \nu}{O_4B \sin \mu}$$



Which gives

$$m_A = \frac{\omega_{in} r_{in}}{\omega_{out} r_{out}} = \frac{V_{in}}{V_{out}} = \frac{c \sin \mu r_{in}}{a \sin \nu r_{out}}$$

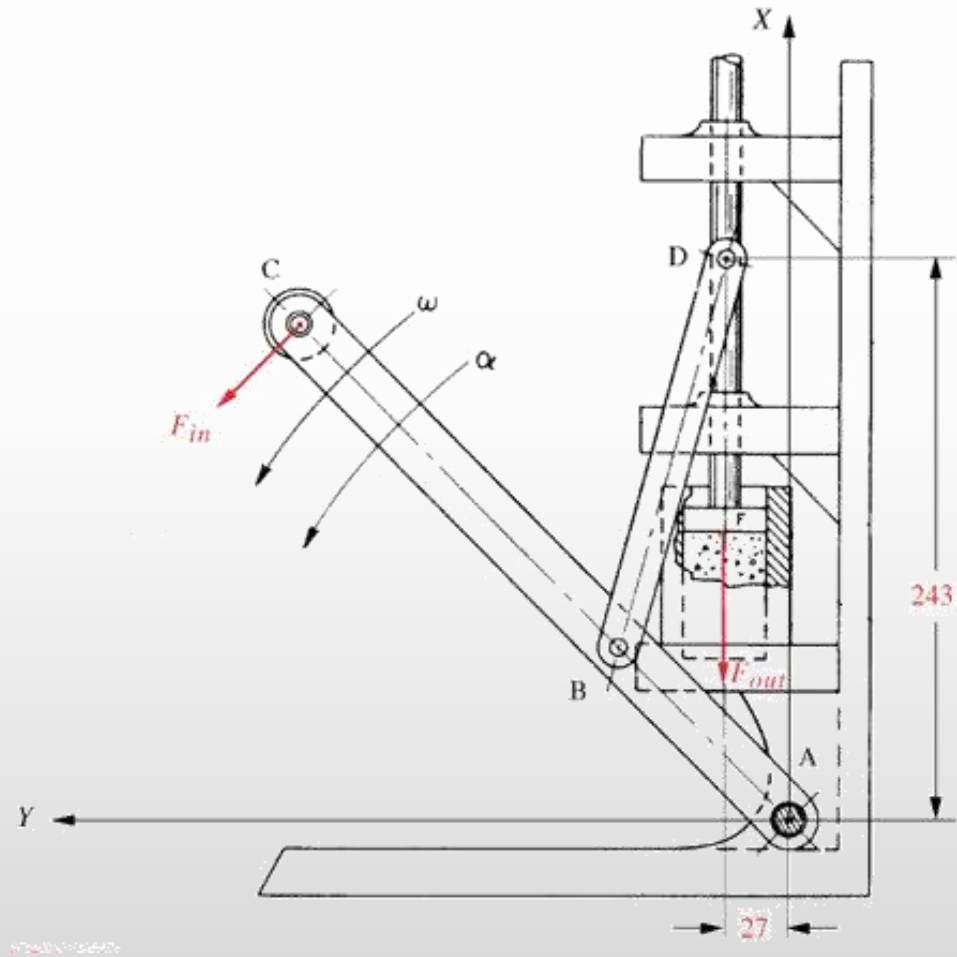
# Example

Calculate the mechanical advantage for the powder compaction mechanism.

$$AB = 105 \text{ mm @ } 44^\circ$$

$$BD = 172 \text{ mm}$$

$$AC = 301 \text{ mm @ } 44^\circ$$



# Example – Solution

From the drawing (offset Slider-Crank):

$$\theta_2 = 44^\circ$$

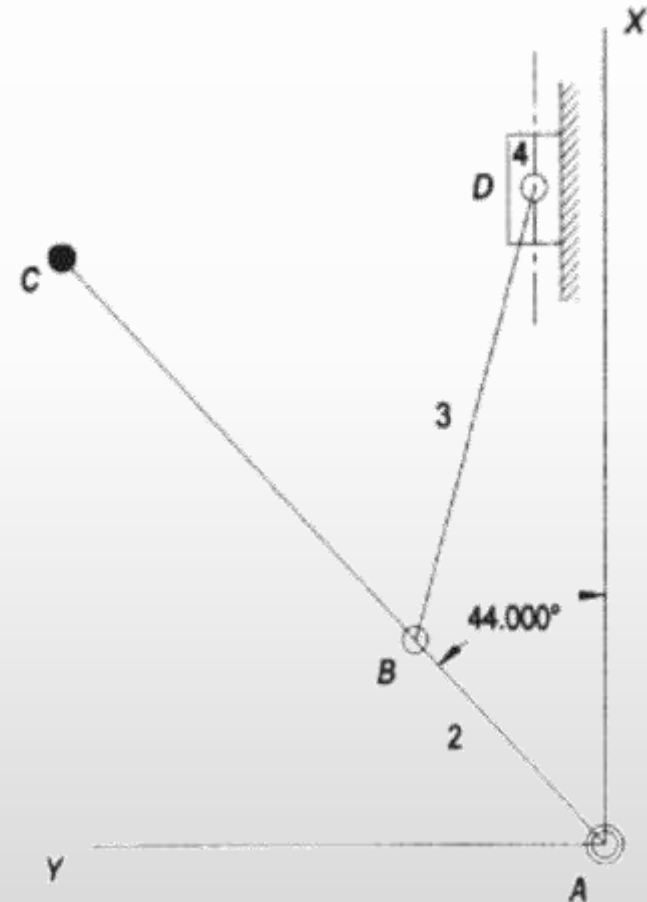
$$r_{in} = AC = 301 \text{ mm}$$

$$a = AB = 105 \text{ mm}$$

$$b = BD = 172 \text{ mm}$$

$$c = 27 \text{ mm}$$

$$d = 243 \text{ mm}$$



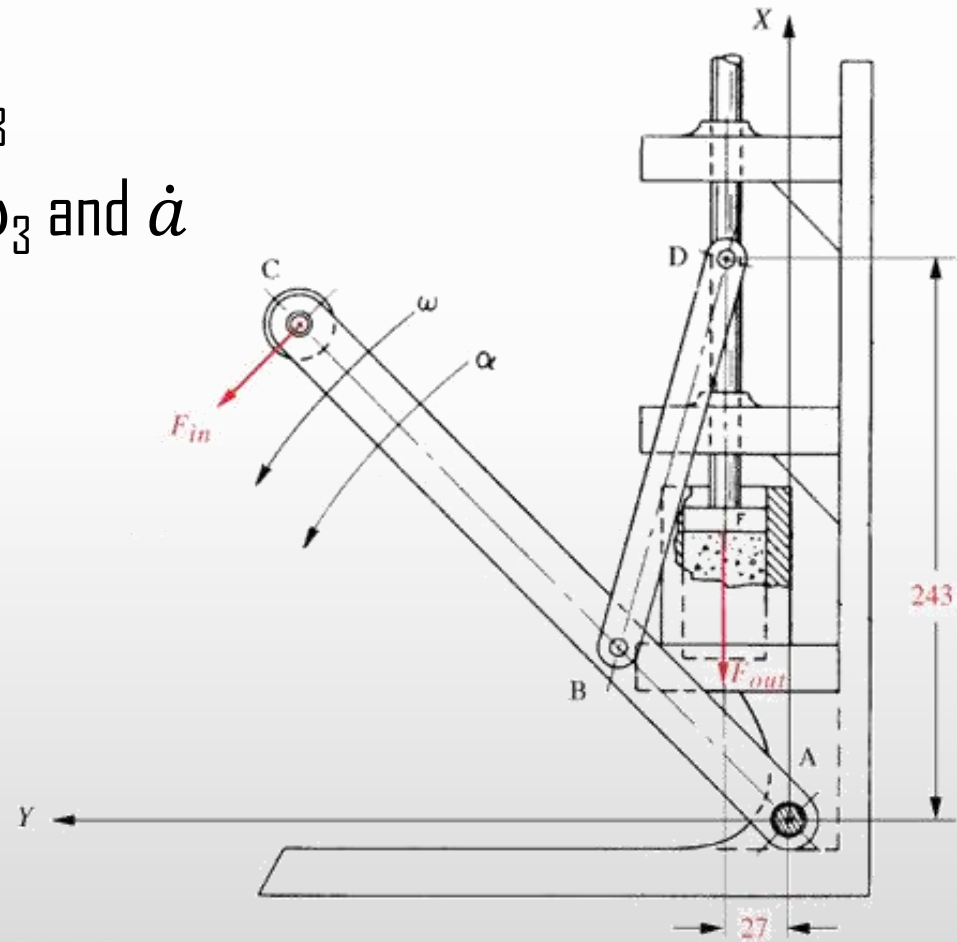


# Example - Steps

**Step 1:** Position analysis > find  $\theta_3$

**Step 2:** Velocity analysis > find  $\omega_3$  and  $\dot{\alpha}$

**Step 3:** Calculate  $m_A = \frac{V_{in}}{V_{out}}$



# Example – Step 1

Find  $\theta_3$  from previous position analysis

$a = 105$  mm,  $b = 172$  mm,

$c = 27$  mm,  $d = 243$  mm,  $\theta_2 = 44^\circ$

$$\theta_3 = \arcsin\left(-\frac{a \sin \theta_2 - c}{b}\right) + \pi = \arcsin\left(-\frac{105 \sin 44^\circ - 27}{172}\right) + \pi = 164.5^\circ$$

## Example – Step 2

Find  $\omega_3$  and  $\dot{a}$  from previous velocity analysis

$$\omega_3 = \frac{a \cos \theta_2}{b \cos \theta_3} \omega_2 = -0.456 \omega_2$$

$$\dot{a} = -a\omega_2 \sin \theta_2 + b\omega_3 \sin \theta_3 = -93.9 \omega_2$$

## Example – Step 3

Calculate the mechanical advantage

$a = 105 \text{ mm}$ ,  $b = 172 \text{ mm}$ ,  $c = 27 \text{ mm}$ ,  $d = 243 \text{ mm}$ ,  $\theta_2 = 44^\circ$

$$V_{out} = |\dot{d}|$$

$$V_{in} = |\omega_{in} r_{in}| = |AC \omega_2|$$

$$m_A = \frac{V_{in}}{V_{out}} = \frac{301 \omega_2}{93.9 \omega_2} = 3.2$$